



FETI methods

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return on innovation

Outline

- FETI: main features
- Rigid body projection

- FETI-2: general methodology for coarse grid preconditioners
- Avoiding dense projector: FETI-DP
- Mixed equations: YADP-FETI

- Time harmonic equations: FETI-H

- Mixed interface conditions: FETI-2LM
- Algebraic approximate optimal interface conditions

- Conclusion

FETI: main features

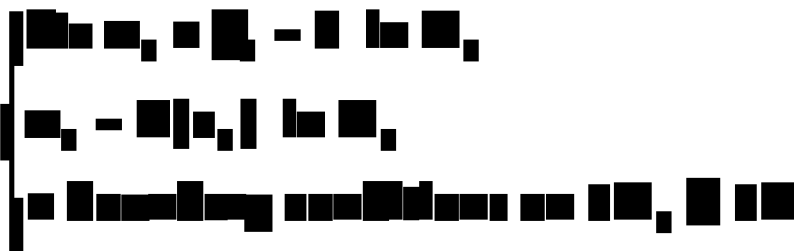
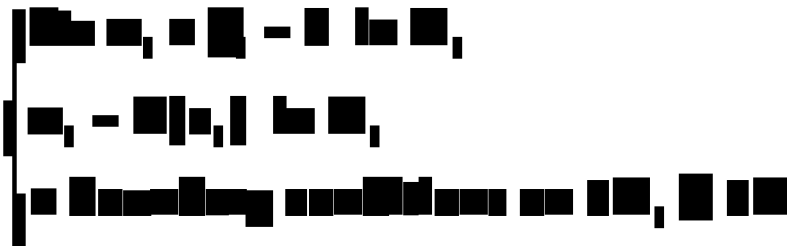
- First method based on Lagrange multipliers
 - ⇒ discontinuous solution
 - ⇒ dual interface variables
- Easy interface management (uncoupling)
- Alternate cheap local preconditioner
- Imbedded coarse grid preconditioner

FETI : continuous model for elasticity

- Global problem

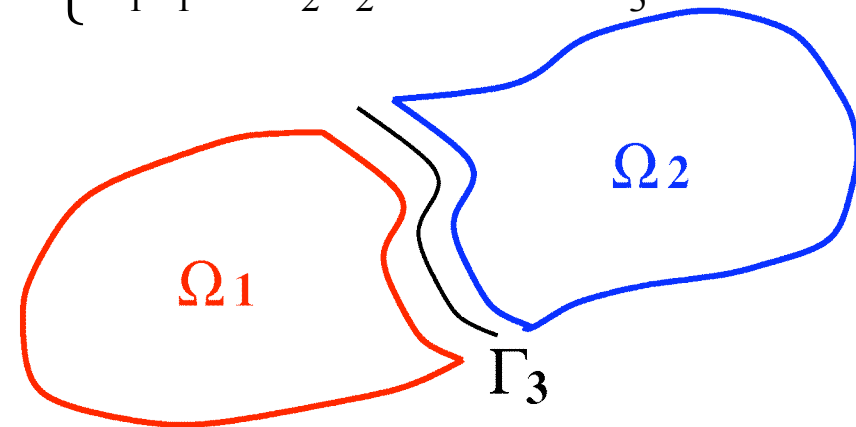


- Local problem



- Interface conditions

$$\begin{cases} u_1 = u_2 \text{ on } \Gamma_3 \\ \sigma_1 n_1 + \sigma_2 n_2 = 0 \text{ on } \Gamma_3 \end{cases}$$

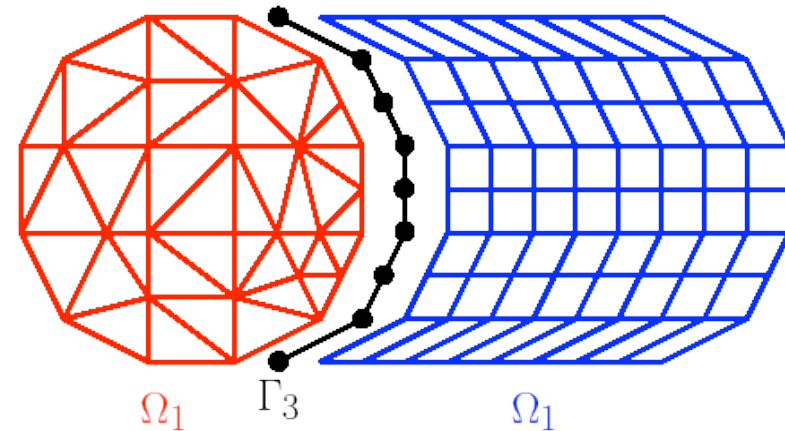
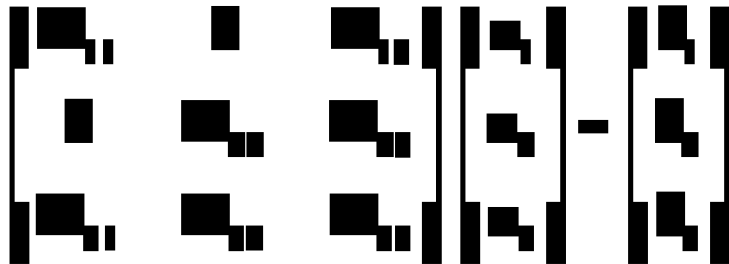


- FETI method :

$$\begin{cases} \sigma_1 n_1 = -\sigma_2 n_2 = \lambda \\ g = u_1 - u_2 = 0 \end{cases}$$

FETI : discrete model

- Global system of equations



- Local systems of equations: Neumann boundary conditions



- Interface problem

$$g = x_3^{(1)} - x_3^{(2)} = 0$$

FETI : algebraic formulation

- Local systems of equations

$$\begin{aligned}
 & \left[\begin{array}{c|c} \mathbf{K}_i & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} \end{array} \right] \begin{bmatrix} \mathbf{u}_i \\ \mathbf{u}_i \end{bmatrix} = \begin{bmatrix} \mathbf{f}_i \\ \mathbf{0} \end{bmatrix} \\
 & \left[\begin{array}{c|c} \mathbf{K}_i & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} \end{array} \right] \begin{bmatrix} \mathbf{u}_i \\ \mathbf{u}_i \end{bmatrix} = \begin{bmatrix} \mathbf{f}_i \\ \mathbf{0} \end{bmatrix}
 \end{aligned}$$

- Elimination of inner variables

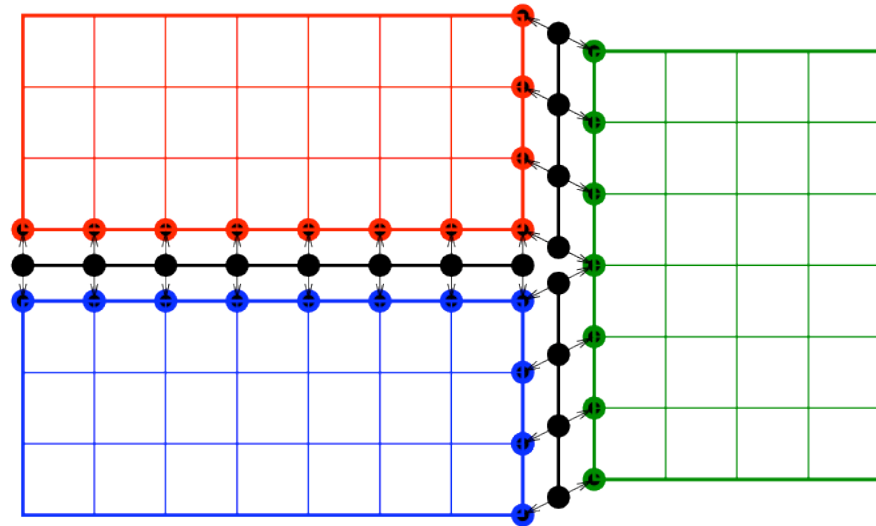
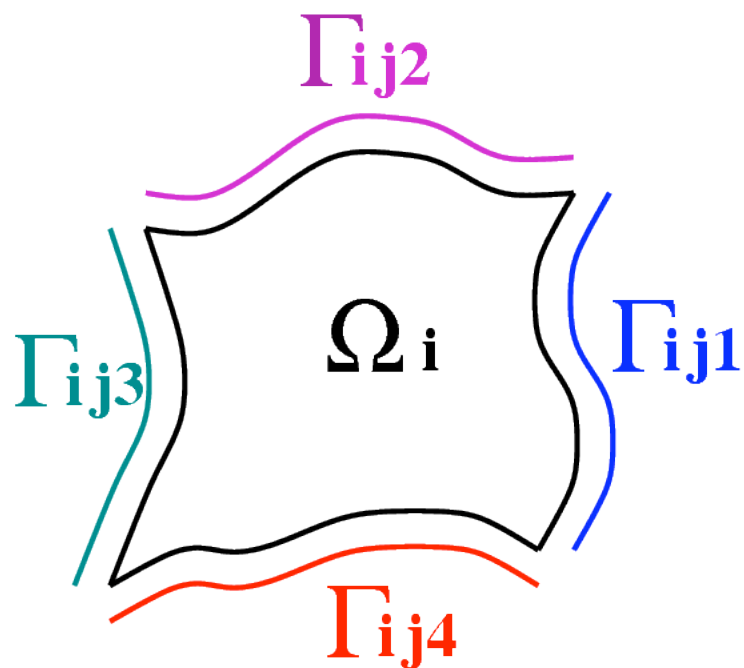
$$\begin{aligned}
 & \left[\begin{array}{c|c} \mathbf{K}_i & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} \end{array} \right] \begin{bmatrix} \mathbf{u}_i \\ \mathbf{u}_i \end{bmatrix} = \begin{bmatrix} \mathbf{f}_i \\ \mathbf{0} \end{bmatrix} \\
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 & \left[\begin{array}{c|c} \mathbf{K}_i & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} \end{array} \right] \begin{bmatrix} \mathbf{u}_i \\ \mathbf{u}_i \end{bmatrix} = \begin{bmatrix} \mathbf{f}_i \\ \mathbf{0} \end{bmatrix}
 \end{aligned}$$

- FETI interface problem

$$\left[\begin{array}{c|c|c} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{array} \right] \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \end{bmatrix} = \begin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \\ \mathbf{f}_3 \end{bmatrix}$$

Easy interface management

- No multiple interface variables



- Uncoupled computation of jump of interface displacements

Optimal local preconditioner

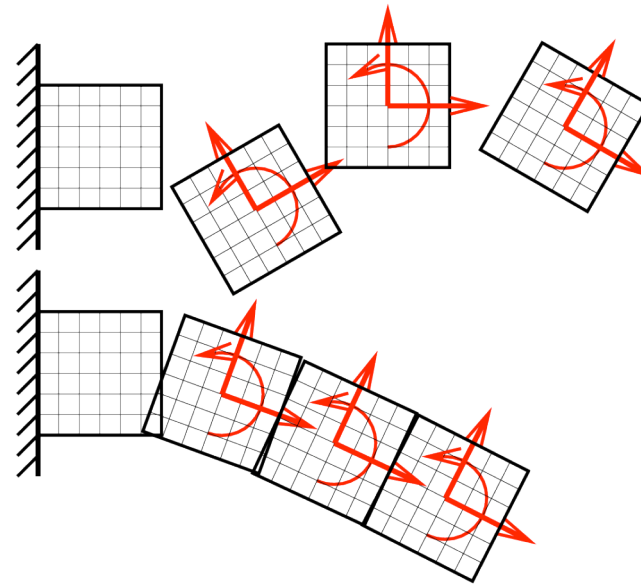
- FETI condensed interface operator
- Optimal local preconditioner (convergence independent of mesh size)
- Computation of preconditioned gradient
- Solution of Dirichlet problem in each subdomain

Lumped local preconditioner

- FETI condensed interface operator
- Optimal local preconditioner
- Lumped local preconditioner
- Inexpensive, very efficient for moderate number of subdomains

Coarse grid preconditioner

- Projection for rigid body motion
 - ⇒ computation of local rigid body motions that minimize interface jump
 - ⇒ solution of global problem whose unknowns are rigid body motions



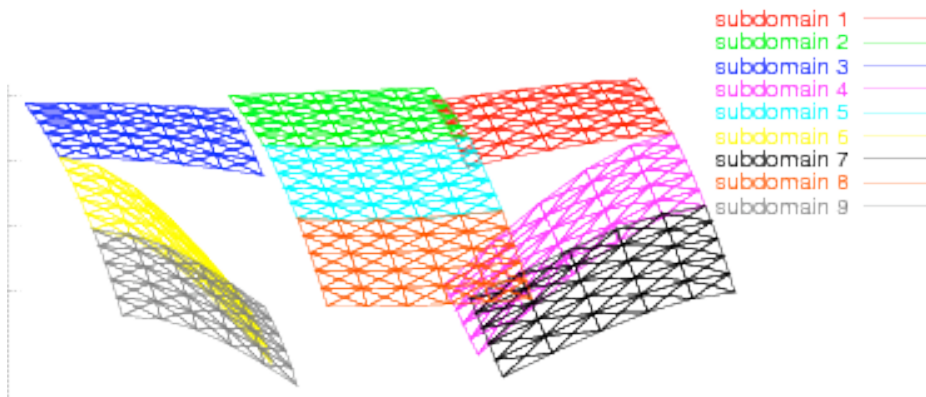
- Global coarse grid preconditioner
 - ⇒ convergence independent upon number of subdomains

FETI-2

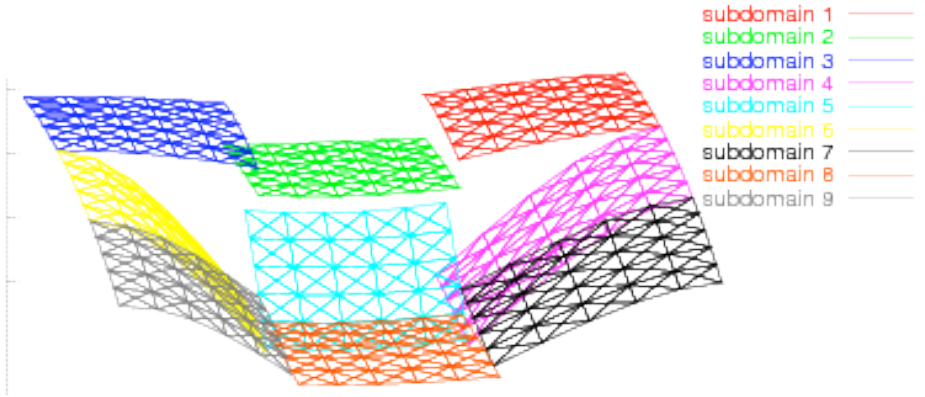
- Second level coarse preconditioner for FETI
- Forming and solving directly interface problem for selected nodes (corners for shell elements)
- Forming and solving directly interface problem for small set of trial interface modes (averaging modes = constant in one space direction, on edges or faces)
- Complex implementation due to rigid body projection
- Although forming the coarse problems requires only solution of local problem for local + neighbors modes, the coarse operator is a full matrix
- A very efficient and simple methodology to build coarse grid preconditioners when there are no rigid body motions

FETI-2 for shell elements

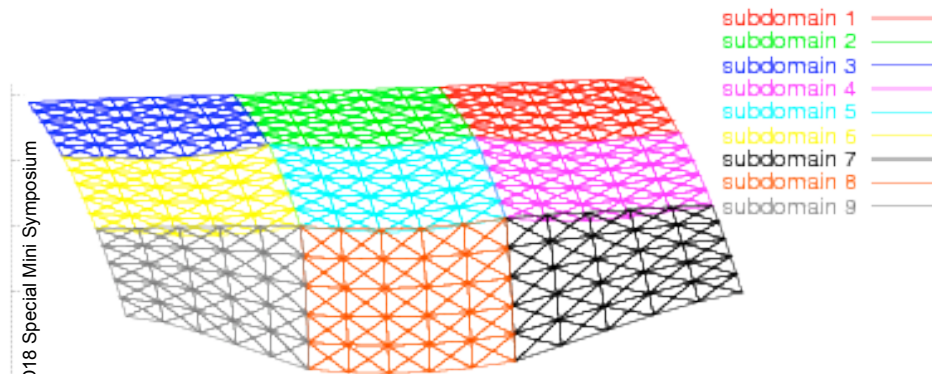
Initial solution without rigid body motion correction



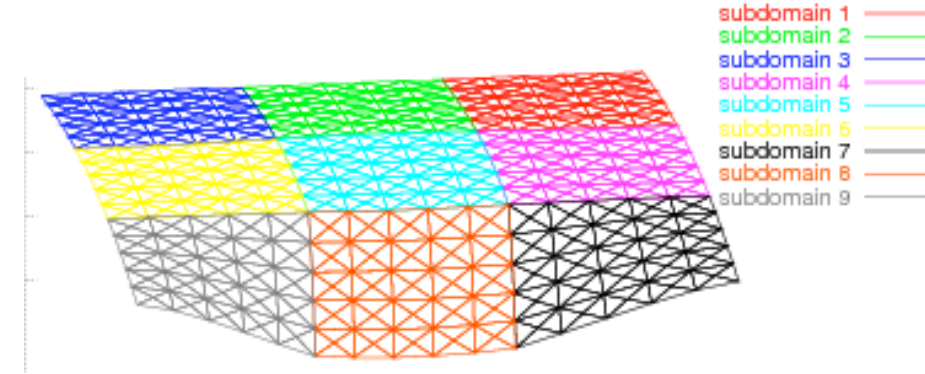
Initial solution without rigid body motion correction



Initial solution with corner correction



Initial solution with both corner and average correction



FETI-DP

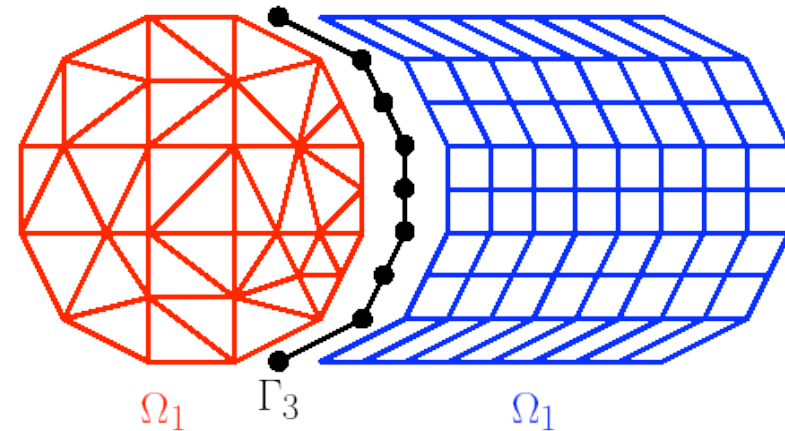
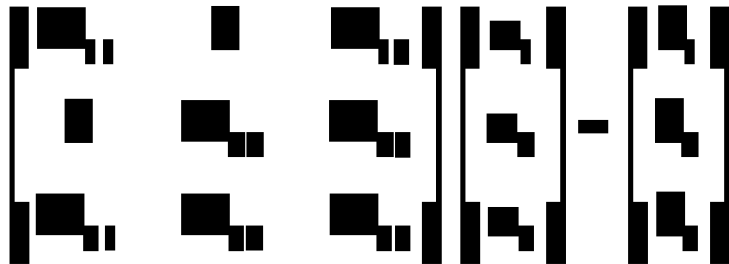
- How to get rid of rigid body motions to get sparse second-level coarse grid preconditioner?
- Add Dirichlet boundary conditions in subdomains
 - ⇒ treat a small number of interface nodes in each subdomain in a primal way (Schur complement)
- In 2D topology (shell), corners
- Mixed variables on the interface
 - ⇒ mostly dual, interaction forces
 - ⇒ occasionally primal, displacements
- But the interface problem is mixed now
 - ⇒ eliminate primal variables in second-level (sparse) coarse grid preconditioner

YADP-FETI

- Mixed problems : Stokes equation, incompressible elasticity
- $\sigma.n$ and pn are forces
- Take $\sigma.n$ and p as interface variables
 - ⇒ Neumann boundary conditions for displacements (dual)
 - ⇒ Dirichlet boundary conditions for pressure (primal)
- Local preconditioner : Dirichlet for displacements and Neumann for pressure
- Two projections
 - ⇒ rigid body motions for the interface problem
 - ⇒ constant pressure modes for the preconditioner (treated like in balanced method)

Arbitrary splitting of the global matrix on interface

- Global system of equations



- Local systems of equations : generalized Robin boundary conditions



- Interface problem, still

$$g = x_3^{(1)} - x_3^{(2)} = 0$$

FETI-H

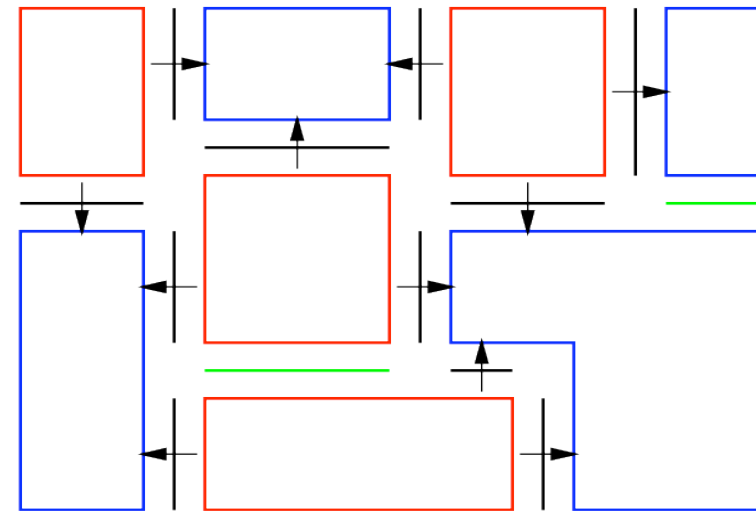
- For Helmholtz equation

$$-\Delta u - k^2 u = f$$

- Augmented matrix associated with inner or outer first order approximate transparent boundary condition

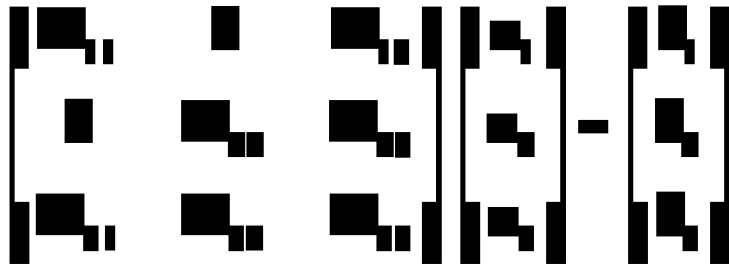
$$\frac{\partial u}{\partial n} \pm iku = \lambda$$

- Well posed local problem if all conditions are inward or outward
- Coloring of subdomains
- Mixing of absorbing and non absorbing interfaces

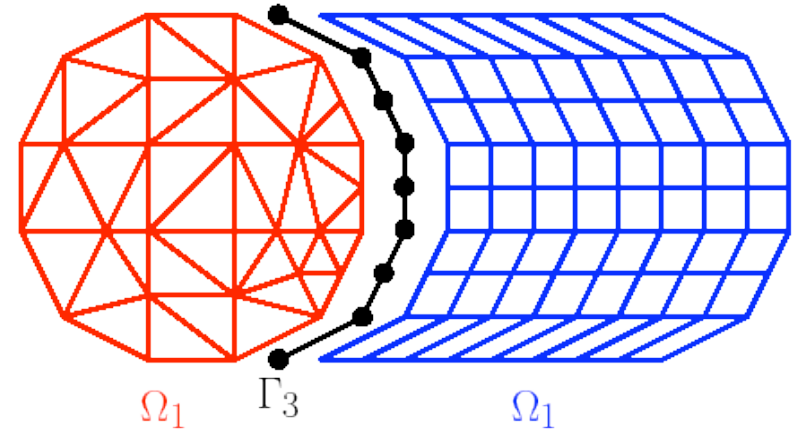


FETI-2LM method

- Global system of equations



- Local system of equations



- Two interface conditions

$$\begin{cases} x_3^{(1)} = x_3^{(2)} \\ K_{31}x_1 + K_{32}x_2 + K_{33}^{(1)}x_3^{(1)} + K_{33}^{(2)}x_3^{(2)} = b_3 \\ \Leftrightarrow \lambda_1 + \lambda_2 - k_1x_3^{(1)} - k_2x_3^{(2)} = 0 \end{cases}$$



Condensed interface problem

- Local static condensation

$$\begin{aligned}
 & \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} F_1 \\ F_2 \end{pmatrix} \\
 & \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} F_1 \\ F_2 \end{pmatrix}
 \end{aligned}$$

- Matrix of interface problem

$$\begin{pmatrix} I & I - (k_1 + k_2)(S^{(2)} + k_2)^{-1} \\ I - (k_2 + k_1)(S^{(1)} + k_1)^{-1} & I \end{pmatrix}$$

Optimal interface connection conditions

- Optimal interface conditions

$$\begin{aligned}
 \begin{bmatrix} \mathbf{K}_1 \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} &= \begin{bmatrix} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{bmatrix} \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \end{bmatrix} - \begin{bmatrix} \mathbf{F}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{F}_3 \end{bmatrix} \\
 \begin{bmatrix} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{bmatrix} &= \begin{bmatrix} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{bmatrix} \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \end{bmatrix} - \begin{bmatrix} \mathbf{F}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{F}_3 \end{bmatrix}
 \end{aligned}$$

- Optimal conditions = static condensation on interface of remaining structure
- Interpretation via local static condensation in global system of equations

$$\begin{bmatrix} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{bmatrix} \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \end{bmatrix} - \begin{bmatrix} \mathbf{F}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{F}_3 \end{bmatrix} = \begin{bmatrix} \mathbf{K}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{K}_3 \end{bmatrix} \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \end{bmatrix} - \begin{bmatrix} \mathbf{F}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{F}_3 \end{bmatrix}$$

Main features of the method

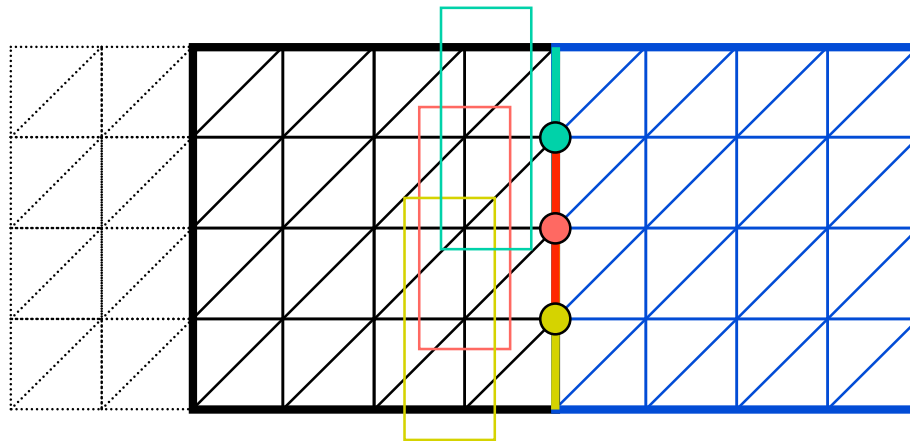
- Well posed local problems, even with irregular mesh splitting
- Convergence in $p - 1$ iterations in case of one-way splitting into p subdomains



- Issue : computation of exact optimal operator impossible (Schur complement)
- Approximation required

Sparse approximation of Schur complement

- Local condensation on small patches
- Weighted assembling



- Purely algebraic approach
- Black box implementation
- Works for any kind of element
- Very fast convergence for highly heterogeneous problems

Conclusion

- Variety of methods depending on what problem to be solved
- Except for primal interface variables in DP methods, uncoupled interfaces
- General methodology of FETI-2 coarse grid preconditioner applies to all methods
- Choice of coarse space easy for coercive problems
- More difficult for wave propagation problems without absorbing terms
- FETI-2LM applies to wide range of problems
- All these methods can be used for non matching grids with mortar elements