Computational advances in quasi-optimal domain decomposition methods for time-harmonic electromagnetic wave problems

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Why Domain Decomposition Methods ?

- We want to solve high-frequency time-harmonic wave problems.
- We also want to use the finite element method.

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■ Large. → Direct solvers do not scale.

Non-Hermitian.
 Iterative solvers do not converge well.

Highly indefinite.

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- Highly indefinite.

→ Iterative solvers do not converge well.

Solution: Domain Decomposition Method!

- 1 Optimized Schwarz algorithm
- 2 Transmission operators
- 3 Preconditioner
- 4 High-order FEM discretizations
- 5 Conclusion

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We start by splitting the computational domain into sub-domains Ω_i.
And we apply the following iterative scheme:

$$\begin{aligned} & \operatorname{curl}\operatorname{curl}\mathbf{e}_{i}^{k} - k^{2}\mathbf{e}_{i}^{k} &= \mathbf{0} & \operatorname{in} \Omega_{i}, \\ & \gamma_{\mathsf{T}}(\mathbf{e}_{i}^{k}) &= -\gamma_{\mathsf{T}}(\mathbf{e}^{\operatorname{inc}}) & \operatorname{on} \Gamma_{i}, \\ & \gamma_{\mathsf{t}}(\operatorname{curl}\mathbf{e}_{i}^{k}) + \mathcal{B}\Big[\gamma_{\mathsf{T}}(\mathbf{e}_{i}^{k})\Big] &= \mathbf{0} & \operatorname{on} \Gamma_{i}^{\infty}, \\ & \gamma_{\mathsf{t}}(\operatorname{curl}\mathbf{e}_{i}^{k}) + \mathcal{S}\Big[\gamma_{\mathsf{T}}(\mathbf{e}_{i}^{k})\Big] &= \mathbf{g}_{ij}^{k-1} & \operatorname{on} \Sigma_{ij}, \\ & \operatorname{with:} & \mathbf{g}_{ij}^{k} = -\mathbf{g}_{ji}^{k-1} + 2\mathcal{S}\Big[\gamma_{\mathsf{T}}(\mathbf{e}_{j}^{k})\Big] & \operatorname{on} \Sigma_{ij}. \end{aligned}$$



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It can be recast into the following linear system:

$$\mathbf{g}^k = \mathcal{A} \Big[\mathbf{g}^{k-1} \Big] + \mathbf{b} \longrightarrow (\mathcal{I} - \mathcal{A}) \mathbf{g} = \mathbf{b}.$$

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Transmission operators — Zeroth and second orders

Zeroth-order:

[Després, 1992]

$$\mathcal{S}\big[\gamma_{\mathsf{T}}\left(\mathbf{e}\right)\big] = \jmath k \, \gamma_{\mathsf{T}}\left(\mathbf{e}\right).$$

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Optimized second-order:

[Dolean, Gander and Gerardo-Giorda, 2009]

[Rawat and Lee, 2010]

[Dolean, Gander, Lanteri, Lee and Peng, 2015]

$$\mathcal{S}\left[\gamma_{\mathsf{T}}\left(\mathbf{e}\right)\right] = \jmath k \left[\mathcal{I} + \frac{\beta}{k^{2}}\operatorname{\mathsf{grad}}_{\Sigma}\operatorname{\mathsf{div}}_{\Sigma}\right]^{-1} \left[\mathcal{I} - \frac{\alpha}{k^{2}}\operatorname{\mathsf{curl}}_{\Sigma}\operatorname{\mathsf{curl}}_{\Sigma}\right] \left[\gamma_{\mathsf{T}}\left(\mathbf{e}\right)\right].$$

• Where α and β are chosen such that optimal convergence rate is obtained.

Transmission operators — On-surface radiation condition

On-surface radiation condition:

[El Bouajaji, Antoine and Geuzaine, 2014]

$$\begin{split} \mathcal{S}\Big[\gamma_{\mathsf{T}}\left(\mathbf{e}\right)\Big] &= \jmath k\Big[\mathcal{I} + \mathbf{grad}_{\Sigma}\,\frac{1}{k_{\varepsilon}^{2}}\,\mathrm{div}_{\Sigma} - \mathbf{curl}_{\Sigma}\,\frac{1}{k_{\varepsilon}^{2}}\,\mathrm{curl}_{\Sigma}\,\Big]^{-1/2} \\ & \Big[\mathcal{I} - \mathbf{curl}_{\Sigma}\,\frac{1}{k_{\varepsilon}^{2}}\,\mathrm{curl}_{\Sigma}\,\Big]\Big[\gamma_{\mathsf{T}}\left(\mathbf{e}\right)\Big]. \end{split}$$

- With $k_{\varepsilon} = k + j\varepsilon$, and ε chosen to reach the optimal convergence rate.
- The square-root operator is non-local.

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On-surface radiation condition:

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- With $k_{\varepsilon} = k + j\varepsilon$, and ε chosen to reach the optimal convergence rate.
- The square-root operator is non-local.
- It is thus localized using Padé decomposition of order N_p, with a rotation of the branch-cut α:

$$(\mathcal{I} + \mathbf{\Delta})^{1/2} \approx R_0(\alpha) - \sum_{l=1}^{N_p} \frac{A_l(\alpha)}{B_l(\alpha)} \Big[\mathcal{I} + B_l(\alpha) \mathbf{\Delta} \Big]^{-1}.$$

 \longrightarrow Where $R_0(\alpha)$, $A_l(\alpha)$ and $B_l(\alpha)$ are the Padé coefficients.

$$\longrightarrow \text{ And } \mathbf{\Delta} = \operatorname{\mathbf{grad}}_{\Sigma} \frac{1}{k_{\varepsilon}^2} \operatorname{div}_{\Sigma} - \operatorname{\mathbf{curl}}_{\Sigma} \frac{1}{k_{\varepsilon}^2} \operatorname{curl}_{\Sigma}.$$

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Let us now study the convergence rate of the previous operators.

Scattering by a sphere taken as test case.



Transmission operators — Benchmark: convergence

Convergence history for different transmission operators.
 No FEM used — 2 sub-domains — No Padé used.



Transmission operators — Benchmark: Padé orders

Convergence history for different Padé orders.
 No FEM used — 2 sub-domains.



Transmission operators — Benchmark: k variations

Iteration count for different wavenumbers.

- ----> FEM used 5 sub-domains.
- → 20 mesh elements per wavelength.



Transmission operators — Benchmark: sub-domains

Iteration count for different number of sub-domains.

- ---- FEM used --- 5 sub-domains.
- → 20 mesh elements per wavelength.



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• Even with the best possible transmission operator, the Schwarz algorithm requires $\mathcal{O}(N)$ iterations.



- The information is propagated only between neighbour sub-domains.
 - Let us consider a 1D waveguide with 10 sub-domains.

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• We need to propagate information globally.

Preconditioner — A simple case

• For simplicity, the iteration operator is renamed.

$$(\mathcal{I}-\mathcal{A})\mathbf{g}=\mathbf{b} \Longleftrightarrow \mathcal{F}\mathbf{g}=\mathbf{b}$$

• For a simple waveguide with no internal reflections, \mathcal{F} is known:



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• Moreover \mathcal{F}_{A}^{-1} is easy to compute explicitly.

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For a simple waveguide with no internal reflections, \mathcal{F} is known:



• Moreover \mathcal{F}_{A}^{-1} is easy to compute explicitly.

 \mathcal{F}_{A}^{-1} can be a good preconditioner!

Preconditioner — Double sweep

- Constructing explicitly \mathcal{F}_A^{-1} is not needed.
- For iterative solvers only the application of \mathcal{F}_A^{-1} is needed.
- The following recursion can be used:

$$\mathbf{h} = \mathcal{F}_{A}^{-1}\mathbf{r} = \begin{cases} \begin{array}{ccc} h_{2,1} &= r_{2,1}, \\ h_{i+1,i} &= r_{i+1,i} - \mathcal{B}_{i}^{f}h_{i,i-1}, \end{array} & \text{Forward sweep} \\ \\ \left\{ \begin{array}{ccc} h_{N-1,N} &= r_{N-1,N}, \\ h_{i-1,i} &= r_{i-1,i} - \mathcal{B}_{i}^{b}h_{i,i+1}. \end{array} \right. \end{array} & \text{Backward sweep} \end{cases}$$

→ Double-sweep.

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Information is accumulated from sub-domain to sub-domain.



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→ Double-sweep.

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Unfortunately this is a sequential scheme.

■ 2D waveguide benchmark — TE mode.

			$\omega = 2$	20π				$\omega = 4$	0π	
N	5	10	25	50	100	5	10	25	50	100
0^{th} order + Precond.	3	3	4	4	4	3	3	4	4	4
0 th order	8	18	48	98	198					
2 nd order + Precond.	3	3	4	4	4	3	3	3	3	4
2 nd order	8	18	46	98	201					
OSRC + Precond.	3	3	3	4	4	3	3	4	4	8
OSRC	8	18	48	119	239					

Preconditioner is robust with respect to ω and N variations.

Preconditioner — Partial sweeps

How to circumvent the sequential nature of the preconditioner?

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Preconditioner applied on independent blocks. Equivalent to a Block-Jacobi applied to \mathcal{F}_A^{-1} .

Preconditioner — Benchmark: setup

- Marmousi benchmark.
- Pressure field on a $[9 \times 3]$ [km] domain.
- Domain decomposed into 256 sub-domains.





Preconditioner — Benchmark: iteration count

Iteration count.



Iteration count stable for sufficiently large sweeps.

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The situation can be improved using high-order FEM discretizations.

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The situation can be improved using high-order FEM discretizations.

- **1** What happens to the DDM iteration count?
- **2** What happens when we mix orders for \mathbf{e}_i and \mathbf{g} ?

Tests on a waveguide with different orders and mesh sizes.
 On-surface radiation condition is used.

High-order FEM discretizations — Iteration count

• What happens to the iteration count?



High-order FEM discretizations — Iteration count

What happens to the iteration count?

Order	Mesh size	Accuracy	Count
1	16	$\overline{ \begin{array}{c} 9.9 \times 10^{-2} \\ 9.8 \times 10^{-2} \end{array} }$	41
2	4		42
2	16	$\begin{array}{c} 7.7 \times 10^{-4} \\ 7.5 \times 10^{-4} \end{array}$	39
4	4		37
3	16	$\begin{array}{c} 2.1 \times 10^{-5} \\ 1.9 \times 10^{-5} \end{array}$	34
4	8		31



Mesh size [per wavelength]

High-order FEM discretizations — Mixing orders

What happens when we mix orders for e_i and g?
 Unknown e_i discretized with an order 4 basis.



• The DDM is no longer equivalent to the non-DDM problem.

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• On-surface radiation condition combined with Padé localization

- ---- Offers high linear solver convergence speed.
- \longrightarrow Robust with respect to a k increase.

Double sweep

----- Limits the iteration count increase with sub-domains.

High-order FEM

- ---- Iteration count decreases when accuracy is increased.
- \longrightarrow Accuracy decreases when mixing orders for \mathbf{e}_i and \mathbf{g}_{\dots}
- → ... but, iteration count decreases also.

Conclusion II

- Open-source implementation available for testing!
- Go to http://onelab.info.
- Download the pre-compiled GetDDM code.
 - Available for MS Windows, MacOS X, and Linux.
 - Makes use of Gmsh and GetDP codes.
- Open Gmsh executable.
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Thank you for your attention!