

Mesoscopic and Macroscopic Mixed Variational Analysis of Two-Phase Flow in Fractured Porous Media

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1 Physical Two-Phase Flow Model

- *Mixed velocity-pressure-saturation governing equations*

$$\left. \begin{aligned} \mathbf{u}_\alpha &= -\frac{\kappa_{r\alpha}(s_\alpha)}{\mu_\alpha} \mathbf{K}(\mathbf{grad} p_\alpha - \rho_\alpha \mathbf{g}) \\ \phi \frac{\partial(\rho_\alpha s_\alpha)}{\partial t} + \mathit{div}(\rho_\alpha \mathbf{u}_\alpha) &= \rho_\alpha \hat{q}_\alpha(s_\alpha) \end{aligned} \right\} \text{in } \Omega \times (0, T) \quad (1)$$

- *Flow volume balance constraint - Capillary pressure*

$$\begin{aligned} s_w + s_n &= 1 \\ p_c(s_w) &= p_n - p_w \end{aligned} \quad (2)$$

2 Fractional Two-Phase Flow Model

[Arbogast 1992, Chen-Ewing 1999]

- *Total velocity - Global pressure - Complementary pressure*

$$\mathbf{u} = \mathbf{u}_w + \mathbf{u}_n$$

$$p = p_n - \int_0^{s_w} \left(f_w \frac{\partial p_c}{\partial s_w} \right)(s) ds \quad (3)$$

$$\theta = - \int_0^{s_w} \left(f_w f_n \frac{\partial p_c}{\partial s_w} \right)(s) ds$$

- *Fractional flow mixed system*

$$\left. \begin{aligned} \lambda^{-1}(\theta) \mathbf{K}^{-1} \mathbf{u} &= -\mathbf{grad} p - \gamma_1(\theta) \\ \mathit{div} \mathbf{u} &= \hat{q}(\theta); \\ \lambda^{-1}(\theta) \mathbf{K}^{-1} \mathbf{u}_w &= -\mathbf{grad} \theta - f_w(\theta) \mathbf{grad} p - \gamma_2(\theta) \\ \vartheta(\theta) \frac{\partial \theta}{\partial t} + \mathit{div} \mathbf{u}_w &= \hat{q}_w(\theta) \end{aligned} \right\} \text{in } \Omega \times (0, T) \quad (4)$$

3 Instantaneous Total Velocity-Global Pressure Mixed Variational Model

[Alduncin 2005]

- *Subdifferential boundary conditions*

$$\begin{aligned} \gamma_{NP} \in \partial\psi_N(\delta_N \mathbf{u}) &= \partial I_{\{\hat{u}\}}(\delta_N \mathbf{u}) \text{ in } B^*(\partial\Omega_N) \\ \gamma_{DP} \in \partial\psi_D(\delta_D \mathbf{u}) &= \{\hat{p}\} \text{ in } B^*(\partial\Omega_D) \end{aligned} \quad (5)$$

- *Variational Green Formula*

$$\mathbf{div}^T q + \mathbf{grad} q = \boldsymbol{\delta}^T \boldsymbol{\gamma} q \text{ in } \mathbf{V}^*(\Omega) \quad (6)$$

- *Fundamental trace compatibility property*

$$(\mathbf{C}_\delta) \quad \delta \in \mathcal{L}(\mathbf{V}(\Omega), B(\partial\Omega)) \text{ is surjective}$$

- *Mixed variational model*

$$(\mathbf{M}) \quad \left\{ \begin{array}{l} \text{Find } \mathbf{u} \in \mathbf{V}(\Omega) \text{ and } p \in Y(\Omega) \\ \mathbf{div}^T p \in (\lambda(\theta(t))\mathbf{K})^{-1}\mathbf{u} + \boldsymbol{\partial}(I_{\{\hat{u}(t)\}} \circ \delta_N)(\mathbf{u}) - \mathbf{f}_\theta^*(t) \text{ in } \mathbf{V}^*(\Omega) \\ -\mathbf{div} \mathbf{u} \in \partial 0_Y(p) - \hat{q}(t) \text{ in } Y^*(\Omega) \end{array} \right.$$

- *Mixed functional framework*

$$\mathbf{V}(\Omega) = \mathbf{H}(\text{div}; \Omega) \equiv \{\mathbf{v} \in \mathbf{L}^2(\Omega) : \text{div } \mathbf{v} \in L^2(\Omega)\}$$

$$Y(\Omega) = L^2(\Omega)$$

$$B(\partial\Omega) = H^{-1/2}(\partial\Omega)$$

$$B^*(\partial\Omega) = H^{1/2}(\partial\Omega)$$

(7)

- *Classical compatibility condition*

$$(\mathbf{C}_{\text{div}}) \text{div} \in \mathcal{L}(\mathbf{V}(\Omega), Y^*(\Omega)) \text{ is surjective}$$

- *Primal composition duality principle*

Theorem 1 *Mixed problem (\mathbf{M}) is uniquely solvable if and only if its instantaneous variational primal problem*

$$(\mathbf{P}) \left\{ \begin{array}{l} \text{Find } \mathbf{u} \in \mathbf{V}(\Omega) \\ \mathbf{0} \in (\lambda(\theta(t))\mathbf{K})^{-1}\mathbf{u} + \partial I_{\mathcal{N}(\text{div})}(\mathbf{u} - \mathbf{u}_{\hat{q}(t)}) + \partial(I_{\{\hat{u}(t)\}} \circ \delta_N)(\mathbf{u}) - \mathbf{f}_\theta^*(t) \end{array} \right. \quad \text{in } \mathbf{V}^*(\Omega)$$

is uniquely solvable, where $\text{div } \mathbf{u}_{\hat{q}(t)} = \hat{q}(t)$

4 Evolution Wetting Velocity-Complementary Pressure Mixed Variational Model

[Alduncin 2007]

- *Evolution mixed functional Hilbert framework*

$$\mathcal{V} = L^2(0, T; \mathbf{V}(\Omega)) = \{\mathbf{v} : (0, T) \rightarrow \mathbf{V}(\Omega) \mid \|\mathbf{v}\|_{\mathcal{V}} = [\int_0^T \|\mathbf{v}(t)\|_{\mathbf{V}(\Omega)}^2 dt]^{1/2} < \infty\}$$

$$\mathcal{Y} = L^2(0, T; Y(\Omega)) = \{y : (0, T) \rightarrow Y(\Omega) \mid \|y\|_{\mathcal{Y}} = [\int_0^T \|y(t)\|_{Y(\Omega)}^2 dt]^{1/2} < \infty\} \quad (8)$$

- *Mixed variational model*

$$(\mathcal{M}) \left\{ \begin{array}{l} \text{Find } \mathbf{u}_w \in \mathcal{V} \text{ and } \theta \in \mathcal{X} \\ \mathbf{div}^T \theta \in \partial F(\mathbf{u}_w) - \mathbf{h}_\theta^* \quad \text{in } \mathcal{V}^* \\ -\mathbf{div} \mathbf{u}_w = A(\theta) \frac{\partial \theta}{\partial t} - \hat{q}_w \quad \text{in } \mathcal{Y}^* \\ \theta(0) = \hat{\theta}_0 \end{array} \right.$$

- *Dual evolution duality principle*

Theorem 2 *Dual evolution mixed problem (\mathcal{M}) possesses a unique solution if and only if its dual evolution nonlinear problem*

$$(\mathcal{D}) \begin{cases} \text{Find } \theta \in \mathcal{X} \\ 0 \in A(\theta) \frac{\partial \theta}{\partial t} + \partial(F^* \circ \mathbf{div}^T)(\theta + r_{h_\theta}^*) - \hat{q}_w \text{ in } \mathcal{Y}^* \\ \theta(0) = \hat{\theta}_0 \end{cases}$$

possesses a unique solution, where $\mathbf{div}^T r_{h_\theta}^ = \mathbf{h}_\theta^*$*

- *Dual evolution solvability*

[Chen 2001]

Theorem 3 *Dual evolution mixed problem (\mathcal{D}) is uniquely solvable*

5 Dual Instantaneous Macro-Hybrid Variational Formulation

[Alduncin 2007]

- *Flow region nonoverlapping domain decomposition*

$$\bar{\Omega} = \bigcup_{e=1}^E \bar{\Omega}_e \quad \Omega_e \cap \Omega_f = \emptyset \quad 1 \leq e < f \leq E$$

$$\Gamma_e = \partial\Omega_e \cap \Omega \quad 1 \leq e \leq E \quad (9)$$

$$\Gamma_{ef} = \Gamma_e \cap \Gamma_f \quad 1 \leq e < f \leq E$$

- *Specific fractured media decomposition*

$$\{\Omega_e\}_{e=1}^{E_R} \quad \text{and} \quad \{\Omega_e\}_{e=E_R+1}^E \quad E = E_R + E_F \quad (10)$$

- *Decomposable total velocity and global pressure Hilbert framework*

$$\mathbf{V}(\Omega) \simeq \left\{ \mathbf{v} \in \mathbf{V}(\{\Omega_e\}) \equiv \prod_{e=1}^E \mathbf{V}(\Omega_e) : \{\delta_{\Gamma_e} \mathbf{v}\} \in \mathbf{Q} \right\} \quad (11)$$

$$Y(\Omega) \simeq \mathbf{Y}(\{\Omega_e\}) \equiv \prod_{e=1}^E Y(\Omega_e)$$

- *Fundamental macro-hybrid compatibility condition*

$$(\mathbf{C}_{[\delta_{\Gamma_e}]}) \quad [\delta_{\Gamma_e}] \in (\mathcal{L}(\mathbf{V}(\{\Omega_e\})), \mathbf{B}(\{\Gamma_e\})) \text{ is surjective}$$

Part II: Macro-Hybrid Variational Formulations

- *Primal and dual internal boundary transmission subspaces*

$$\mathbf{Q} \subset \mathbf{B}(\{\Gamma_e\}) = H^{1/2}(\{\Gamma_e\}) \tag{12}$$

$$\mathbf{Q}^* = \left\{ \{\mu_e^*\} \in \mathbf{B}^*(\{\Gamma_e\}) : \langle \{\mu_e^*\}, \{\mu_e\} \rangle_{B(\{\Gamma_e\})} = 0, \forall \{\mu_e\} \in \mathbf{Q} \right\}$$

Lemma 4 *Due to $(\mathbf{C}_{[\delta_{\Gamma_e}]})$, macro-hybrid compositional dualization holds true*

$$\{\delta_{\Gamma_e}^T \lambda_e^*\} \in \partial(I_Q \circ [\delta_{\Gamma_e}])(\{\mathbf{u}_e\}) \iff \{\delta_{\Gamma_e} \mathbf{u}_e\} \in \partial \mathbf{I}_{Q^*}(\{\lambda_e^*\}) \tag{13}$$

- *Instantaneous macro-hybrid dual mixed problem*

$$(\mathbf{MH}) \left\{ \begin{array}{l}
 \text{Find } \{\mathbf{u}_e\} \in \mathbf{V}(\{\Omega_e\}) \text{ and } \{p_e\} \in \mathbf{Y}(\{\Omega_e\}) \\
 \{\mathbf{div}^T p_e\} - \{\delta_{\Gamma_e}^T \lambda_e^*\} \in \{(\lambda(\theta_e(t)) \mathbf{K}_e)^{-1} \mathbf{u}_e\} \\
 \quad + \partial(I_{\{\widehat{u}_e(t)\}} \circ [\delta_{N_e}])(\{\mathbf{u}_e\}) - \{\mathbf{f}_{\theta_e}^*(t)\} \quad \text{in } \mathbf{V}^*(\{\Omega_e\}) \\
 -\{\mathbf{div} \mathbf{u}_e\} \in \{\partial 0_{Y_e}(p_e)\} - \{\widehat{q}_e(t)\} \quad \text{in } \mathbf{Y}^*(\{\Omega_e\}) \\
 \text{and } \{\lambda_e^*\} \in \mathbf{B}^*(\{\Gamma_e\}) \text{ satisfying the dual synchronizing condition} \\
 \{\delta_{\Gamma_e} \mathbf{u}_e\} \in \partial \mathbf{I}_{Q^*}(\{\lambda_e^*\}) \text{ in } \mathbf{B}(\{\Gamma_e\})
 \end{array} \right.$$

6 Dual Evolution Macro-Hybrid Variational Formulation

- *Dual evolution macro-hybrid mixed problem*

$$(\mathcal{MH}) \left\{ \begin{array}{l}
 \text{Find } \{\mathbf{u}_{w_e}\} \in \mathbf{V}_{\{\Omega_e\}} \text{ and } \{\theta_e\} \in \mathbf{X}_{\{\Omega_e\}} \\
 \{\mathbf{div}^T \theta_e\} - \{\delta_{\Gamma_e}^T \chi_e^*\} \in \{\partial \mathbf{F}(\mathbf{u}_{w_e})\} - \{h_{\theta_e}^*\} \text{ in } \mathbf{V}_{\{\Omega_e\}}^* \\
 \{-\mathbf{div} \mathbf{u}_{w_e}\} = \left\{ A_e(\theta_e) \frac{\partial \theta_e}{\partial t} \right\} - \{\hat{q}_{w_e}\} \quad \text{in } \mathbf{Y}_{\{\Omega_e\}}^* \\
 \{\theta_e(0)\} = \{\hat{\theta}_{0_e}\} \\
 \text{and } \{\chi_e^*\} \in \mathbf{B}_{\{\Gamma_e\}}^* \text{ satisfying the dual synchronizing condition} \\
 \{\delta_{\Gamma_e} \mathbf{u}_{w_e}\} \in \partial \mathbf{I}_{Q^*}(\{\chi_e^*\}) \text{ in } \mathbf{B}_{\{\Gamma_e\}}
 \end{array} \right.$$

Part III: Macroscopic Fractional Flow Models

[Alboin 2000]

- *Specific fractured media decomposition*

$$\{\Omega_e\}_{e=1}^{E_R} \quad \text{and} \quad \{\Omega_e\}_{e=E_R+1}^E \quad E = E_R + E_F \quad (14)$$

- *Macro-scaling asymptotic process*

fracture-system $\{\Omega_f\}_{f=E_R+1}^E \longrightarrow$ fracture interface-system $\{\Gamma_f\}_{f=E_R+1}^E$

- *Interaction surfaces*

$$\Sigma_{ef} = \partial\Omega_e \cap \Gamma_f \quad 1 \leq e \leq E_R, \quad E_R + 1 \leq f \leq E \quad (15)$$

- *Fracture interface-system pressure contributions*

$$-\left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} p_f \right\} \quad \text{and} \quad -\left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} \theta_f \right\} \quad (16)$$

- *Rock-system source contributions*

$$-\left\{ \frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_e \right\} \quad \text{and} \quad -\left\{ \frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_{w,e} \right\} \quad (17)$$

7 Macroscopic Fractional Fow Problem for the Rock-System

- *Fracture interface-system pressure contribution*

$$-\left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} p_f \right\} \quad (18)$$

- *Instantaneous total velocity-global pressure-interface global pressure macro-hybrid dual mixed problem*

$$(\widetilde{MH}_R) \left\{ \begin{array}{l}
 \text{Find } \{\mathbf{u}_e\} \in \mathbf{V}(\{\Omega_e\}) \text{ and } \{p_e\} \in \mathbf{Y}(\{\Omega_e\}) \\
 \{\mathbf{div}^T p_e\} - \{\delta_{\Gamma_e}^T \lambda_e^*\} \in \{(\lambda(\theta_e(t)) \mathbf{K}_e)^{-1} \mathbf{u}_e\} + \partial(I_{\{\widehat{u}_e(t)\}} \circ [\delta_e])(\{\mathbf{u}_e\}) \\
 -\{\mathbf{f}_{\theta_e}^*(t)\} - \left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} p_f \right\} \quad \text{in } \mathbf{V}^*(\{\Omega_e\}) \\
 -\{\mathbf{div} \mathbf{u}_e\} \in \{\partial 0_{Y_e}(p_e)\} - \{\widehat{q}_e(t)\} \quad \text{in } \mathbf{Y}^*(\{\Omega_e\}) \\
 \text{and } \{\lambda_e^*\} \in \mathbf{B}^*(\{\Gamma_e\}) \text{ satisfying the dual synchronizing condition} \\
 \{\delta_{\Gamma_e} \mathbf{u}_e\} \in \partial \mathbf{I}_{Q^*}(\{\lambda_e^*\}) \quad \text{in } \mathbf{B}(\{\Gamma_e\})
 \end{array} \right.$$

- *Fracture interface-system pressure contribution*

$$-\left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} \theta_f \right\} \quad (19)$$

- *Evolution wetting velocity-complementary pressure-interface complementary pressure macro-hybrid dual mixed problem*

$$(\mathcal{MH}\mathcal{R}) \left\{ \begin{array}{l}
 \text{Find } \{\mathbf{u}_{w_e}\} \in \mathbf{V}_{\{\Omega_e\}} \text{ and } \{\theta_e\} \in \mathbf{X}_{\{\Omega_e\}} \\
 \{\mathbf{div}^T \theta_e\} - \{\delta_{\Gamma_e}^T \chi_e^*\} \in \{\partial \mathbf{F}(\mathbf{u}_{w_e})\} - \{\mathbf{h}_{\theta_e}^*\} \\
 -\left\{ \sum_{f=E_R+1}^E \delta_{\Sigma_{ef}}^T \gamma_{\Sigma_{ef}} \theta_f \right\} \quad \text{in } \mathbf{V}^*_{\{\Omega_e\}} \\
 \{-\mathbf{div} \mathbf{u}_{w_e}\} = \left\{ A_e(\theta_e) \frac{\partial \theta_e}{\partial t} \right\} - \{\hat{q}_{w_e}\}, \quad \text{in } \mathbf{Y}^*_{\{\Omega_e\}} \\
 \{\theta_e(0)\} = \{\hat{\theta}_{0_e}\} \\
 \text{and } \{\chi_e^*\} \in \mathbf{B}^*_{\{\Gamma_e\}} \text{ satisfying the dual synchronizing condition} \\
 \{\delta_{\Gamma_e} \mathbf{u}_{w_e}\} \in \partial \mathbf{I}_{Q^*}(\{\chi_e^*\}), \quad \text{in } \mathbf{B}_{\{\Gamma_e\}}
 \end{array} \right.$$

8 Macroscopic Fractional Flow Problem for the Fracture Interface-System

- *Fracture interface internal boundaries and interfaces*

$$\begin{aligned} \mathcal{I}_f &= f = E_R + 1, \dots, E \\ \mathcal{I}_{fg} = \mathcal{I}_f \cap \mathcal{I}_g &= E_R + 1 \leq f < g \leq E \end{aligned} \quad (20)$$

- *Rock-system source contribution*

$$-\left\{ \frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_e \right\} \quad (21)$$

- *Instantaneous total velocity-global pressure-interface global pressure macro-hybrid dual mixed problem*

$$(\widetilde{MH}_F) \left\{ \begin{array}{l} \text{Find } \{\mathbf{u}_e\} \in \mathbf{V}(\{\Gamma_e\}) \text{ and } \{p_e\} \in \mathbf{Y}(\{\Gamma_e\}) \\ \{\mathbf{div}^T p_e\} - \{\delta_{\Gamma_e}^T \lambda_e^*\} \in \{(\lambda(\theta_e(t)) \mathbf{K}_e)^{-1} \mathbf{u}_e\} \\ \quad + \partial(I_{\{\widehat{u}_e(t)\}} \circ [\delta_e])(\{\mathbf{u}_e\}) - \{\mathbf{f}_{\theta_e}^*(t)\} \quad \text{in } \mathbf{V}^*(\{\Gamma_e\}) \\ -\{\mathbf{div} \mathbf{u}_e\} \in \{\partial 0_{Y_e}(p_e)\} - \{\widehat{q}_e(t)\} - \left\{ \frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_e \right\} \text{ in } \mathbf{Y}^*(\{\Gamma_e\}) \\ \text{and } \{\lambda_e^*\} \in \mathbf{B}^*(\{\mathcal{I}_e\}) \text{ satisfying the dual synchronizing condition} \\ \{\delta_{\Gamma_e} \mathbf{u}_e\} \in \partial \mathbf{I}_{Q^*}(\{\lambda_e^*\}) \quad \text{in } \mathbf{B}(\{\mathcal{I}_e\}) \end{array} \right.$$

- *Rock-system source contribution*

$$-\left\{\frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_{w,e}\right\} \quad (22)$$

- *Evolution wetting velocity-complementary pressure-interface complementary pressure macro-hybrid dual mixed problem*

$$(\widetilde{\mathcal{MH}}_{\mathcal{F}}) \left\{ \begin{array}{l} \text{Find } \{\mathbf{u}_{w_e}\} \in \mathbf{V}_{\{\Gamma_e\}} \text{ and } \{\theta_e\} \in \mathbf{X}_{\{\Gamma_e\}} \\ \{\operatorname{div}^T \theta_e\} - \{\delta_{\Gamma_e}^T \chi_e^*\} \in \{\partial \mathbf{F}(\mathbf{u}_{w_e})\} - \{\mathbf{h}_{\theta_e}^*\} \quad \text{in } \mathbf{V}^*_{\{\Gamma_e\}} \\ \{-\operatorname{div} \mathbf{u}_{w_e}\} = \left\{A_e(\theta_e) \frac{\partial \theta_e}{\partial t}\right\} - \{\hat{q}_{w_e}\} - \left\{\frac{1}{d} \sum_{e=1}^{E_R} \gamma_{\Sigma_{ef}}^T \delta_{\Sigma_{ef}} \mathbf{u}_{w,e}\right\} \text{ in } \mathbf{Y}^*_{\{\Sigma_{ef}\}} \\ \{\theta_e(0)\} = \{\hat{\theta}_{0_e}\} \\ \text{and } \{\chi_e^*\} \in \mathbf{B}^*_{\{\mathcal{I}_e\}} \text{ satisfying the dual synchronizing condition} \\ \{\delta_{\Gamma_e} \mathbf{u}_{w_e}\} \in \partial \mathbf{I}_{Q^*}(\{\chi_e^*\}) \quad \text{in } \mathbf{B}_{\{\mathcal{I}_e\}} \end{array} \right.$$

9 Two-Field Instantaneous Algorithms

- Models (\mathbf{MH}) and $(\widetilde{\mathbf{M}}\widetilde{\mathbf{H}}_R)$ - $(\widetilde{\mathbf{M}}\widetilde{\mathbf{H}}_F)$ expressed in a classical mixed subdifferential form

$$(\mathbf{S}) \left\{ \begin{array}{l} \text{Find } \mathbf{u} \in \mathcal{D}(\mathcal{A}) \subset \mathbf{V} \text{ and } \mathbf{p}^* \in \mathcal{D}(G^*) \subset \mathbf{Y}^* \\ -\Lambda^T \mathbf{p}^* \in \mathcal{A}(\mathbf{u}) \text{ in } \mathbf{V}^* \\ \Lambda \mathbf{u} \in \partial G^*(\mathbf{p}^*) \text{ in } \mathbf{Y} \end{array} \right.$$

- Proximation augmented interpretation

$$(\mathbf{S}_r) \left\{ \begin{array}{l} \text{Find } \mathbf{u} \in \mathcal{D}(\mathcal{A}) \subset \mathbf{V} \text{ and } \mathbf{p}^* \in \mathcal{D}(G^*) \subset \mathbf{Y}^* \\ -\Lambda^T (\mathbf{p}^* - \mathbf{M}^{-*} \text{Prox}_{\mathbf{M}^{-*}, rG \circ (1/r)I_Y}(\mathbf{M}^* \mathbf{p}^* + r\Lambda \mathbf{u})) \\ \in (\mathcal{A} + r\Lambda^T \mathbf{M}^{-*} \Lambda)(\mathbf{u}) \text{ in } \mathbf{V}^* \\ \mathbf{p}^* = (\mathbf{M}^{-*} - \mathbf{M}^{-*} \text{Prox}_{\mathbf{M}^{-*}, rG \circ (1/r)I_Y})(\mathbf{M}^* \mathbf{p}^* + r\Lambda \mathbf{u}) \text{ in } \mathbf{Y}^* \end{array} \right.$$

- *Uzawa type algorithm*

Algorithm I Given $\mathbf{u}^0 \in \mathcal{D}(\mathcal{A})$, $\mathbf{p}_0^* \in \mathcal{D}(G^*)$, known \mathbf{u}^m , \mathbf{p}_m^* , $m \geq 0$
find \mathbf{u}^{m+1} and \mathbf{p}_{m+1}^*

$$\begin{aligned}
 & -\Lambda^T(\mathbf{p}_m^* - \mathbf{M}^{-*} \mathbf{Prox}_{\mathbf{M}^{-*}, rG \circ (1/r)I_Y}(\mathbf{M}^* \mathbf{p}_m^* + r\Lambda \mathbf{u}^m)) \\
 & \in (\mathcal{A} + r\Lambda^T \mathbf{M}^{-*} \Lambda)(\mathbf{u}^{m+1}) \quad \text{in } \mathbf{V}^*
 \end{aligned}$$

$$\mathbf{p}_{m+1}^* = (\mathbf{M}^{-*} - \mathbf{M}^{-*} \mathbf{Prox}_{\mathbf{M}^{-*}, rG \circ (1/r)I_Y})(\mathbf{M}^* \mathbf{p}_m^* + r\Lambda \mathbf{u}^{m+1}) \quad \text{in } \mathbf{Y}^*$$

Theorem 5 *Proximal-point Algorithm I is convergent whenever the dual operator condition*

$(\mathbf{C}_{\mathcal{A}_\Lambda^*, \partial G^*}) \quad -\Lambda \mathcal{A}^{-1}(-\Lambda^T(\cdot)) + \partial G^* : \mathbf{Y}^* \rightarrow \mathbf{2}^{\mathbf{Y}}$ *is maximal monotone holds true*

10 Three-Field Instantaneous Algorithms

- *Intermediate third primal field*

$$\boldsymbol{\tau} = \boldsymbol{\Lambda} \boldsymbol{u} \in \boldsymbol{Y} \quad (23)$$

- *Models (\mathbf{MH}) and $(\widetilde{\mathbf{M}}\widetilde{\mathbf{H}}_R)$ - $(\widetilde{\mathbf{M}}\widetilde{\mathbf{H}}_F)$ expressed in an extended classical three-field mixed subdifferential form*

$$(\mathcal{S}) \left\{ \begin{array}{l} \text{Find } (\boldsymbol{u}, \boldsymbol{\tau}) \in \mathcal{D}(\mathcal{A}) \times \mathcal{D}(G) \subset \boldsymbol{V} \times \boldsymbol{Y} \text{ and } \boldsymbol{p}^* \in \mathcal{D}(G^*) \subset \boldsymbol{Y}^* \\ -\boldsymbol{\Lambda}^T \boldsymbol{p}^* \in \mathcal{A}(\boldsymbol{u}) \quad \text{in } \boldsymbol{V}^* \\ \boldsymbol{p}^* \in \partial G(\boldsymbol{\tau}) \quad \text{in } \boldsymbol{Y}^* \\ \boldsymbol{\Lambda} \boldsymbol{u} - \boldsymbol{\tau} \in \partial \mathbf{0}_{\boldsymbol{Y}^*}(\boldsymbol{p}^*) \text{ in } \boldsymbol{Y} \end{array} \right.$$

- *Proximation augmented interpretation*

$$(\mathcal{S}_r) \left\{ \begin{array}{l} \text{Find } (\mathbf{u}, \boldsymbol{\tau}) \in \mathcal{D}(\mathcal{A}) \times \mathcal{D}(G) \subset \mathbf{V} \times \mathbf{Y} \text{ and } \mathbf{p}^* \in \mathcal{D}(G^*) \subset \mathbf{Y}^* \\ -\Lambda^T(\mathbf{p}^* - r\mathbf{M}^{-*}\boldsymbol{\tau}) \in (\mathcal{A} + r\Lambda^T\mathbf{M}^{-*}\Lambda)(\mathbf{u}) \text{ in } \mathbf{V}^* \\ \mathbf{p}^* + r\mathbf{M}^{-*}\Lambda\mathbf{u} \in \partial G(\boldsymbol{\tau}) + r\mathbf{M}^{-*}\boldsymbol{\tau} \text{ in } \mathbf{Y}^* \\ \mathbf{p}^* = \mathbf{p}^* + r\mathbf{M}^{-*}(\Lambda\mathbf{u} - \boldsymbol{\tau}) \text{ in } \mathbf{Y}^* \end{array} \right.$$

- *Uzawa type algorithm*

Algorithm II Given $\mathbf{p}_0^* \in \mathcal{D}(G^*)$, known \mathbf{p}_m^* , find \mathbf{u}^{m+1} , $\boldsymbol{\tau}^{m+1}$ and \mathbf{p}_{m+1}^*

$$-\Lambda^T(\mathbf{p}_m^* - r\mathbf{M}^{-*}\boldsymbol{\tau}^{m+1}) \in (\mathcal{A} + r\Lambda^T\mathbf{M}^{-*}\Lambda)(\mathbf{u}^{m+1}) \text{ in } \mathbf{V}^*$$

$$\mathbf{p}_m^* + r\mathbf{M}^{-*}\Lambda\mathbf{u}^{m+1} \in \partial G(\boldsymbol{\tau}^{m+1}) + r\mathbf{M}^{-*}\boldsymbol{\tau}^{m+1} \text{ in } \mathbf{Y}^*$$

$$\mathbf{p}_{m+1}^* = \mathbf{p}_m^* + r\mathbf{M}^{-*}(\Lambda\mathbf{u}^{m+1} - \boldsymbol{\tau}^{m+1}) \text{ in } \mathbf{Y}^*$$

Theorem 6 *Proximal-point Algorithm II is convergent whenever the dual operator condition*

$(\mathbf{C}_{\mathcal{A}_\Lambda^*, \partial G^*}) -\Lambda\mathcal{A}^{-1}(-\Lambda^T(\cdot)) + \partial G^* : \mathbf{Y}^* \rightarrow \mathbf{2}^{\mathbf{Y}}$ *is maximal monotone is fulfilled*

- For mesoscopic (\mathcal{MH}) and, similarly, macroscopic dual evolution macro-hybrid mixed problems (\mathcal{MH}_R)-(\mathcal{MH}_F)

11 The Operator Splitting Douglas-Rachford Scheme

- Parallel proximal realization with intermediate hybrid vector

$$\{\kappa_e^{m+1}\} = \{\delta_{\Gamma_e} \mathbf{u}_e^{m+1}\} \in \partial \mathbf{I}_{Q^*}(\{\overline{\chi_e^{*m+1}}\}) \subset \mathcal{B}_{\{\Gamma_e\}} \quad (24)$$

Algorithm $\mathbf{I}_{\mathcal{MH}}$ Given $\{\mathbf{u}_{w_e}^0\} \in \mathcal{V}_{\{\Omega_e\}}$, $\{\theta_e^0\} \in \mathbf{Y}(\{\Omega_e\})$, $\{\chi_e^{*0}\} \in \mathbf{Q}^*$
 known $\{u_e^m\}$, $\{\theta_e^m\}$, $\{\chi_e^{*m}\}$, $m \geq 0$
 find $\{\kappa_e^{m+1}\}$ satisfying the primal synchronizing condition

$$\{\kappa_e^{m+1}\} = \mathbf{Proj}_Q \left(\left\{ \frac{1}{r} A_e(\theta_e^m) \chi_e^{*m} + \delta_{\Gamma_e} u_e^m \right\} \right)$$

and, in parallel, u_e^{m+1} , θ_e^{m+1} , χ_e^{*m+1} , $e = 1, 2, \dots, E$

$$\mathbf{div}^T \theta_e^m - \delta_{\Gamma_e}^T (\chi_e^{*m} - r \kappa_e^{m+1})$$

$$\in (\partial \mathbf{F} + r \mathbf{div}^T A_e^{-1}(\theta_e^m) \mathbf{div} + r \delta_{\Gamma_e}^T \delta_{\Gamma_e})(\mathbf{u}_{w_e}^m) - \mathbf{h}_{\theta_e}^{*m} - \mathbf{div}^T M_e^{-*} \hat{q}_{w_e}^{m+1}$$

$$\theta_e^{m+1} = \theta_e^m + r A_e^{-1}(\theta_e^m) (-\mathbf{div} u_e^{m+1} + \hat{q}_{w_e}^{m+1})$$

$$\chi_e^{*m+1} = \chi_e^{*m} + r (\delta_{\Gamma_e} u_e^{m+1} - \kappa_e^{m+1})$$

12 The Operator Splitting Peaceman-Rachford Scheme

- *Parallel proximal realization with intermediate hybrid vector*

$$\{\kappa_e^{m+1}\} = \{\delta_{\Gamma_e} \mathbf{u}_e^m\} \in \partial \mathbf{I}_{\mathbf{Q}^*}(\{\chi_e^{*m+1/2}\}) \subset \mathcal{B}_{\{\Gamma_e\}} \quad (25)$$

Algorithm II_{MH} Given $\{\mathbf{u}_{w_e}^0\} \in \mathcal{V}_{\{\Omega_e\}}$, $\{\theta_e^0\} \in \mathbf{Y}(\{\Omega_e\})$, $\{\chi_e^{*0}\} \in \mathbf{Q}^*$
 known $\{\mathbf{u}_e^m\}$, $\{\theta_e^m\}$, $\{\chi_e^{*m}\}$, $m \geq 0$
 find $\{\kappa_e^{m+1}\}$ satisfying the primal synchronizing condition

$$\{\kappa_e^{m+1}\} = \mathbf{Proj}_{\mathbf{Q}} \left(\left\{ \frac{1}{r} A_e(\theta_e^m) \chi_e^{*m} + \delta_{\Gamma_e} \mathbf{u}_e^m \right\} \right)$$

and, in parallel, θ_e^{*m+1} , χ_e^{*m+1} , \mathbf{u}_e^{m+1} , θ_e^{m+1} , χ_e^{*m+1} , $e = 1, 2, \dots, E$

$$\theta_e^{*m+1} = \theta_e^{*m} + r/2 A_e^{-1}(\theta_e^m) (-\operatorname{div} \mathbf{u}_e^m + \hat{q}_{w_e}^m)$$

$$\chi_e^{*m+1} = \chi_e^{*m} + r/2 (\delta_{\Gamma_e} \mathbf{u}_e^m - \kappa_e^{m+1})$$

$$\operatorname{div}^T \theta_e^{*m+1/2} - \delta_{\Gamma_e}^T (\chi_e^{*m+1/2} - r \kappa_e^{m+1})$$

$$\in (\partial \mathbf{F} + r \operatorname{div}^T A_e^{-1}(\theta_e^m) \operatorname{div} + r/2 \delta_{\Gamma_e}^T \delta_{\Gamma_e}) (\mathbf{u}_{w_e}^{m+1}) - \mathbf{h}_{\theta_e}^{*m+1} - r/2 \operatorname{div}^T A_e^{-1}(\theta_e^m)$$

$$\theta_e^{*m+1} = \theta_e^{*m+1/2} + r/2 A_e^{-1}(\theta_e^m) (-\operatorname{div} \mathbf{u}_e^{m+1} + \hat{q}_{w_e}^{m+1})$$

$$\chi_e^{*m+1} = \chi_e^{*m+1/2} + r/2 (\delta_{\Gamma_e} \mathbf{u}_e^{m+1} - \kappa_e^{m+1})$$

13 Convergence of the Operator Splitting Schemes

- Mosco's dual operator of $\mathbf{A}_{h_\theta^*} = [\partial F_e](\cdot) - \{h_{\theta_e}^*\}$ relative to coupling operator $\mathbf{D} = ([-div], [\delta_{\Gamma_e}])$

$$\mathbf{A}_{h_\theta^*, D}^*(\boldsymbol{\mu}, \boldsymbol{\nu}^*) \equiv (\mathbf{A}_{h_\theta^*, -div}^*(\boldsymbol{\mu}), \mathbf{A}_{h_\theta^*, \delta_{\Gamma_e}}^*(\boldsymbol{\nu}^*)) = \{(\boldsymbol{\xi}, \boldsymbol{\zeta}^*) \in \mathcal{Y}_{\{\Omega_e\}} \times \mathcal{B}^*_{\{\Gamma_e\}} : \}$$

$$\exists \boldsymbol{\beta} \in \mathcal{Y}_{\{\Omega_e\}}, \boldsymbol{\xi}^* = [div]\boldsymbol{\beta}, \boldsymbol{\zeta}^* = -[\delta_{\Gamma_e}]\boldsymbol{\beta}, -[div^T]\boldsymbol{\mu}^* - [\delta_{\Gamma_e}^T]\boldsymbol{\nu}^* \in \mathbf{A}_{h_\theta^*}(\boldsymbol{\beta})\}$$

- Auxiliary dual supervector $\mathbf{s}^* \in \mathcal{Y}_{\{\Omega_e\}} \times \mathcal{B}^*_{\{\Gamma_e\}}$

$$\mathcal{M}^* \mathbf{s}^* \in (\mathcal{M}^* + r\mathbf{A}_{h_\theta^*, D}^*)(\{\theta_e\}, \{\chi_e^*\}) \iff (\{\theta_e\}, \{\chi_e^*\}) = \mathbf{J}_{\mathcal{M}^*, \mathbf{A}_{h_\theta^*, D}^*}(\mathcal{M}^* \mathbf{s}^*)$$

- Douglas-Rachford macro-hybrid dual problem at $m+1 \geq 1$ time step

$$(\mathbf{D}^{m+1}) \left\{ \begin{array}{l} \text{Given } \{\theta_e^0 = \hat{\theta}_{0_e} \in Z(\Omega_e)\}, \{\chi_e^{*0}\} \in \mathcal{Q}^*, \mathbf{s}^{*m-1} \in \mathcal{Y}_{\{\Omega_e\}} \times \mathcal{B}^*_{\{\Gamma_e\}} \\ \text{find } \{\theta_e^{*m+1}\}, \{\chi_e^{*m+1}\} \text{ and } \{\mathbf{s}_e^{*m}\} \\ \\ \mathcal{M}^* \mathbf{s}^{*m} \in (\mathcal{M}^* + r\mathbf{A}_{h_\theta^*, D}^*)(\{\theta_e^{*m+1}\}, \{\chi_e^{*m+1}\}) \\ \\ 2\mathcal{M}^*(\{\theta_e^{*m}\}, \{\chi_e^{*m}\}) - \mathcal{M}^* \mathbf{s}^{*m-1} \\ \\ \in (\mathcal{M}^* + r\partial\mathcal{G}^*)((\{\theta_e^{*m}\}, \{\chi_e^{*m}\}) + \mathbf{s}^{*m} - \mathbf{s}^{*m-1}) \end{array} \right.$$

Part V: Proximation Semi-Implicit Time Marching Schemes

- *Peaceman-Rachford macro-hybrid dual problem at $m + 1 \geq 1$*

$$(\mathbf{D}^{\widetilde{m+1}}) \left\{ \begin{array}{l} \text{Given } \{\theta_e^0 = \widehat{\theta}_{0_e} \in Z(\Omega_e)\}, \{\chi_e^{*0}\} \in \mathcal{Q}^*, \mathbf{s}^{*-1} \in \mathcal{Y}_{\{\Omega_e\}} \times \mathcal{B}^*_{\{\Gamma_e\}} \\ \text{find } \{\theta_e^{m+1}\}, \{\chi_e^{*m+1}\} \text{ and } \{\mathbf{s}_e^m\} \\ \\ \mathcal{M}^* \mathbf{s}^{*m} \in (\mathcal{M}^* + r/2 \mathbf{A}_{h_\theta^*, D}^*)(\{\theta_e^{*m+1}\}, \{\chi_e^{*m+1}\}) \\ \\ 2\mathcal{M}^*(\{\theta_e^{*m}\}, \{\chi_e^{*m}\}) - \mathcal{M}^* \mathbf{s}^{*m-1} \\ \\ \in (\mathcal{M}^* + r\partial\mathcal{G}^*)(\{\theta_e^{*m}\}, \{\chi_e^{*m}\}) + r/2 \mathbf{s}^{*m} - r/2 \mathbf{s}^{*m-1} \end{array} \right.$$

Theorem 6 *Let dual operators $\mathbf{A}_{h_\theta^*, -div}^*$ and $\mathbf{A}_{h_\theta^*, \delta\Gamma_e}^*$ be maximal monotone. Then, for time-independent data $\mathbf{f}^{*m} = \mathbf{f}^*$, $\mathbf{w}_g^{m+1} = \mathbf{w}_g$, operator splitting algorithms **Algorithm I** $_{\mathcal{MH}}$ and **Algorithm II** $_{\mathcal{MH}}$ evolve, as $m \rightarrow \infty$, to a \mathbf{D}^{m+1} - and a $\mathbf{D}^{\widetilde{m+1}}$ -stationary state of the dual evolution macro-hybrid mixed problem (\mathcal{MH}) , respectively*

Conclusions

- *Subdifferential variational modeling in subsurface flow: theory à la Moreau-Duvaut-Lions-Temam-Le Tallec*
- *Coupling surjectivity compatibility for compositional dualization*
- *Dual stationary and evolution solvability duality principles*
- *Variational macro-hybridization for scaling, localization, multi-constitutivity, multi-algorithmia and parallel computing*
- *Proximation augmented penalty-duality stationary algorithms*
- *Proximation realization of semi-implicit time marching schemes*
- *Variational basis for semi-discrete and fully discrete approximations*